

Lecture 6 (16/7/2019)

Recall the definition of linear independence:

V ... vector space over $F = \mathbb{Q}, \mathbb{R}, \mathbb{C}$

definition $\left[\begin{array}{l} v_1, v_2, \dots, v_n \in V \text{ are said to be lin. ind. if the equation} \\ c_1 v_1 + c_2 v_2 + \dots + c_n v_n = \underset{\substack{\uparrow \\ \text{zero vector in } V}}{0} \\ \text{has only one solution: } c_1 = c_2 = \dots = c_n = 0. \end{array} \right.$

Like in $\mathbb{R}^n$, we have an equivalent definition of linear independence as follows:

equivalent definition $\left[\begin{array}{l} v_1, v_2, \dots, v_n \text{ are lin. ind. if none of them can be written} \\ \text{as a linear combination of the others.} \end{array} \right.$

Like in $\mathbb{R}^n$, we can define basis of a vector space as follows.

definition $\left[\begin{array}{l} V \dots \text{vector space over } F = \mathbb{Q}, \mathbb{R}, \mathbb{C}. \text{ A subset } S \subset V \\ \text{is said to be a basis of } V \text{ if } S \text{ is linearly independent} \\ \text{and spans } V. \end{array} \right.$

An infinite set S is linearly independent if any finite subset of S is linearly independent.

We have an equivalent definition of basis as follows:

equivalent definition $\left[\begin{array}{l} \text{A subset } S \subset V \text{ is a basis of } V \text{ if every vector in} \\ V \text{ has a unique representation as linear combination of} \\ \text{vectors in } S. \end{array} \right.$

$\dim_F V = \#S$ (which can be ∞).

Ex: $V_n =$ set of all polynomials with coefficients in F of degree $\leq n$.

This is a vector space over F .

Note: as standard convention, 0 is a polynomial of degree $-\infty$.

Why? Note that an element of V_n is a function from F to F . Thus, $V_n \subset \underbrace{F^F}_{\text{vector space over } F}$

V_n satisfies 3 properties:

- $0 \in V_n$
- closed under addition: because the sum of two poly. of degree $\leq n$ is still a poly. of degree $\leq n$.
- closed under scaling: because the product of a poly. by a constant is still a poly. of degree $\leq n$.

What is a basis of V_n ?

A vector in V_n is of the form

$$y = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 \quad \text{where } a_0, a_1, \dots, a_n \in F.$$

If we denote

$$y_n = x^n, y_{n-1} = x^{n-1}, \dots, y_1 = x, y_0 = 1$$

Then $y_n, y_{n-1}, \dots, y_1, y_0$ belong to V_n and

$$y = a_n y_n + a_{n-1} y_{n-1} + \dots + a_1 y_1 + a_0 y_0$$

In other words, y is a linear combination of $y_0, y_1, \dots, y_n$.

In other words, $y_0, y_1, \dots, y_n$ span V_n .

Are $y_0, y_1, y_2, \dots, y_n$ linearly independent?

We will solve the equation

$$c_0 y_0 + c_1 y_1 + \dots + c_n y_n = 0 \quad (*)$$

for $c_0, c_1, \dots, c_n$. If this equation turns out to have only one solution $c_0 = c_1 = \dots = c_n = 0$ then we conclude that $y_0, \dots, y_n$ are linearly independent.

Equation (*) can be rewritten as

$$c_0 + c_1x + c_2x^2 + \dots + c_nx^n = 0 \quad \forall x \in F$$

We want to show that $c_0, c_1, \dots, c_n = 0$. Suppose by contradiction that not all $c_0, c_1, \dots, c_n$ are equal to zero. Then LHS is a nonzero polynomial. Then it has at most n roots. This is a contradiction because every $x \in F$ is a root of LHS. Therefore, $c_0, c_1, \dots, c_n = 0$.